MATH 2551-C/HP MIDTERM 1 VERSION A SPRING 2025 COVERS SECTIONS 12.1-12.6, 13.1-13.4, 14.1-2

Full name:	GT ID:
Honor code statement: I will abide strictly by the Georgia will not use a calculator. I will not reference any website, appearance. I will not consult with my notes or anyone during the anyone else during this exam.	oplication, or other CAS-enabled
() I attest to my integrity.	

Read all instructions carefully before beginning.

- Print your name and GT ID neatly above.
- You have 75 minutes to take the exam.
- You may not use aids of any kind.
- The Learning Outcomes for the exam are listed on the back of this front cover. The Formula Sheet is on the final page and may be removed.
- Show your work. Answers without work shown will receive little or no credit.
- Good luck! Write yourself a message of encouragement on the front page!

Points
1
1
2
6
10
10
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50

Learning Outcomes

- G1: Lines and Planes. Describe lines using the vector equation of a line. Describe planes using the general equation of a plane. Find the equations of planes using a point and a normal vector. Find the intersections of lines and planes. Describe the relationships of lines and planes to each other. Solve problems with lines and planes.
- G2: Calculus of Curves. Compute tangent vectors to parametric curves; velocity, speed, and acceleration. Find equations of tangent lines to parametric curves. Solve initial value problems for motion on parametric curves.
- G3: Geometry of Curves. Compute the arc length of a curve in two or three dimensions. Use arc length to solve problems. Compute normal vectors and curvature for curves in two and three dimensions. Interpret these objects geometrically and in application.
- **G4:** Surfaces. Graph cylinders from equations. Describe and find traces on surfaces. Identify standard quadric surfaces including: spheres, ellipsoids, elliptic paraboloid, hyperboloids, cones, hyperbolic paraboloid. Sketch quadric surfaces. Graph functions of two variables and determine their domains and ranges. Graph level curves.
- **G5:** Limits of Functions. Calculate the limits of functions of two variables or determine if they do not exist. Apply the Two-Path Test to show limits do not exist. Define continuity of a function of two or more variables.

For problems 1-2 choose whether each statement is true or false. If the statement is *always* true, pick true. If the statement is *ever* false, pick false. Be sure to neatly fill in the bubble corresponding to your answer choice.

1. (1 point) [G2: Calculus of Curves] For any smooth curve C in space parameterized by a function $\mathbf{r}(t)$, $\mathbf{r}'(t)$ is orthogonal to $\mathbf{r}''(t)$.

○ TRUE ○ FALSE

2. (1 point) [G1: Lines and Planes] Two planes orthogonal to a third plane are parallel to each other.

 \bigcirc TRUE \bigcirc FALSE

3. (2 points) [G4: Surfaces] The domain of the function

$$f(x,y) = \frac{\ln(4-y^2)}{\sqrt{1-x^2}}$$

is which of the following?

- \bigcirc **A)** All of \mathbb{R}^2
- OB) The region on one side of a line
- O C) The interior of a disk
- O D) The interior of a rectangle
- \bigcirc **E)** None of the above

4. (6 points) [G4: Surfaces] Create a contour plot for the function

$$f(x,y) = e^{1-x^2 - y^2}.$$

Your plot should include at least three level curves, be carefully labelled, and you should include work showing how you determined the level curves for full credit. Choose your level curves carefully!

- 5. [G1: Lines and Planes] Let P_1 be the plane 2x+y-z=1 and P_2 be the plane x+3z=3.
 - (a) (2 points) Show that P_1 and P_2 are intersecting planes.

(b) (2 points) Find normal vectors to both planes.

(c) (4 points) Find a parameterization of the line of intersection of the two planes.

(d) (2 points) Find a plane which is orthogonal to both P_1 and P_2 and contains the point (1,1,1).

6. [G2: Calculus of Curves] A drone has lost access to its GPS mid-flight and is now lost! Thankfully, the pilot can still see the drone's velocity, given by

$$\mathbf{v}(t) = \langle \sin(t) + 4, -2\cos(t) - 2, \cos(2t) + 1 \rangle \ m/s$$

for t in seconds.

(a) (4 points) If the drone started at the origin, find an expression for the position of the drone at time t.

- (b) (2 points) What is the drone's position at time $t = \pi$? In what direction is it flying at time $t = \pi$?
- (c) (2 points) Find an equation for the line tangent to the drone's flight path when $t = \pi$.
- (d) (2 points) The drone's destination is at $(2 + 40\pi, -2\pi, \pi)$ m. If the plane loses the ability to steer left and right (in the x and y-directions) at time $t = \pi$, but can still steer up and down (in the z-direction), can the drone make it to its destination? Justify your answer.

7. [G3: Geometry of Curves] Consider the curve C parameterized by

$$\mathbf{r}(t) = \langle 4\ln(t), 4t^2, 8t \rangle, \ 1 \le t \le e^2.$$

(a) (8 points) Compute the length of C.

(b) (2 points) Is $\mathbf{r}(t)$ an arc-length parameterization of C? Justify your answer.

8. [G5: Limits of Functions] Compute each limit below or show that it does not exist.

(a) (2 points)
$$\lim_{(x,y)\to(1,1)} \frac{e^{x^2-y}}{\ln(x+y)}$$

(b) (4 points)
$$\lim_{(x,y)\to(1,1)} \frac{x^2-y^2}{3x^2+2xy-5y^2}$$

(c) (4 points)
$$\lim_{(x,y)\to(0,1)} \frac{2x(y-1)}{x^2+3(y-1)^2}$$

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FORMULA SHEET - DO NOT WRITE

FORMULA SHEET

- Dot product: $\langle u_1, u_2, u_3 \rangle \cdot \langle v_1, v_2, v_3 \rangle = u_1 v_1 + u_2 v_2 + u_3 v_3$
- Dot product magnitudes: $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos(\theta)$
- Cross product: $\langle u_1, u_2, u_3 \rangle \times \langle v_1, v_2, v_3 \rangle = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$
- Cross product magnitude: $\|\mathbf{u} \times \mathbf{v}\| = \|\mathbf{u}\| \|\mathbf{v}\| |\sin(\theta)|$
- Tangent line to a curve $\mathbf{r}(t)$ at t = a: $\ell(t) = \mathbf{r}(a) + \mathbf{r}'(a)(t-a)$
- Arc length: $L = \int_a^b \|\mathbf{r}'(t)\| dt$
- Arc length function: $s(t) = \int_{t_0}^{t} ||\mathbf{r}'(T)|| \ dT$
- Unit tangent vector: $\mathbf{T} = \frac{\mathbf{v}}{\|\mathbf{v}\|} = \frac{d\mathbf{r}}{ds}$
- Curvature: $\kappa = \left\| \frac{d\mathbf{T}}{ds} \right\| = \frac{1}{\|\mathbf{v}\|} \left\| \frac{d\mathbf{T}}{dt} \right\| = \frac{\|\mathbf{v} \times \mathbf{a}\|}{\|\mathbf{v}\|^3}$
- Principal unit normal vector: $\mathbf{N} = \frac{1}{\kappa} \frac{d\mathbf{T}}{ds} = \frac{d\mathbf{T}/dt}{\|d\mathbf{T}/dt\|}$
- Two-Path Test: If there exist two different paths C_1 and C_2 through the point (a, b) along which the limit of f(x, y) takes on different values, then

$$\lim_{(x,y)\to(a,b)} f(x,y)$$

does not exist.